

# ESTIMATION OF REAL-TIME ORIGIN-DESTINATION FLOW USING MOBILE SENSOR NETWORK

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# Presentation Agenda

- Introduction
- O-D Estimation Techniques Overview
- Proposed Estimation Framework
- Preliminary Results
- Future Study

# Introduction

## Origin-destination (O-D) demand

- represents the travel demand of people in the transportation network
- is the corner stone of sound transportation planning
- is the vital part of dynamic traffic management

## Conventional O-D estimation techniques

- Large scale survey
- Demand modeling based on socioeconomic characteristics

## OD estimation technique based on link flow

- Estimation from network traffic flows

$$V_l^k = \sum_i \sum_j D_{ij}^k p_{ij}^{lk} \quad (0 < p_{ij}^{lk} < 1)$$

$V_l^k$  -traffic volume on link l at kth time interval

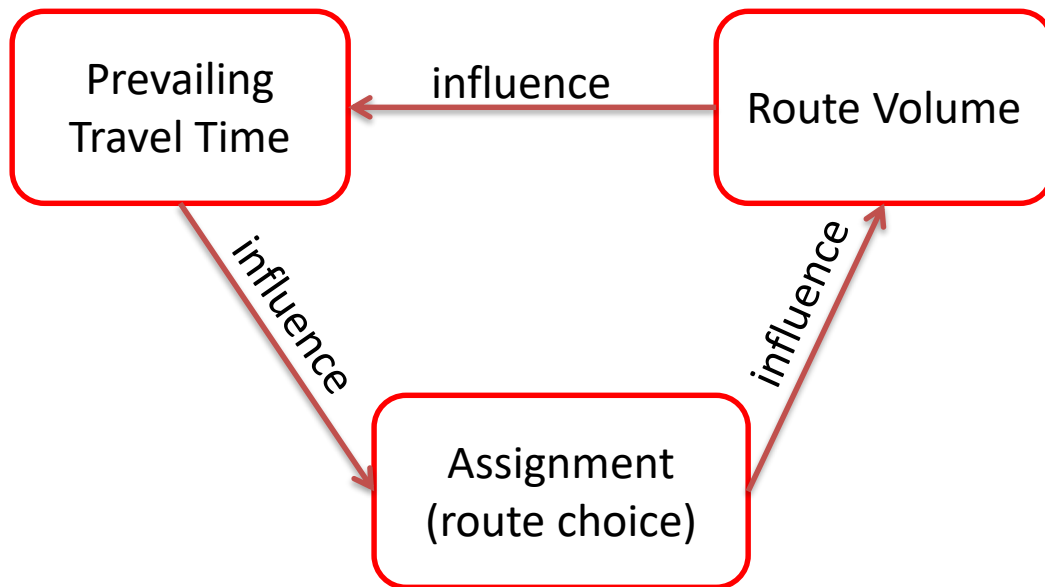
$D_{ij}^k$  -demand from origin i to destination j at kth time interval

$p_{ij}^{lk}$  -portion of the the demand from i to j assigned to link l at kth time interval

# Research Motivation

- Dynamic O-D estimations in academic realm typically suffer high computational expenses and therefore are not quite suitable for practical implementation.
- With the emergence of advanced ITS devices(e.g. Bluetooth Readers, RTMS's), a practical analytical framework with reduced calculations could be developed for operation management purpose.
- The ever-increasing needs for a better and more comprehensive work zone monitoring and impact study (e.g. NJDOT I-295 Direct Connect Project).

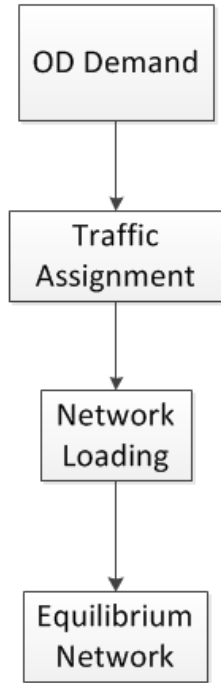
# Module Interaction under Dynamic Traffic Assignment Scheme



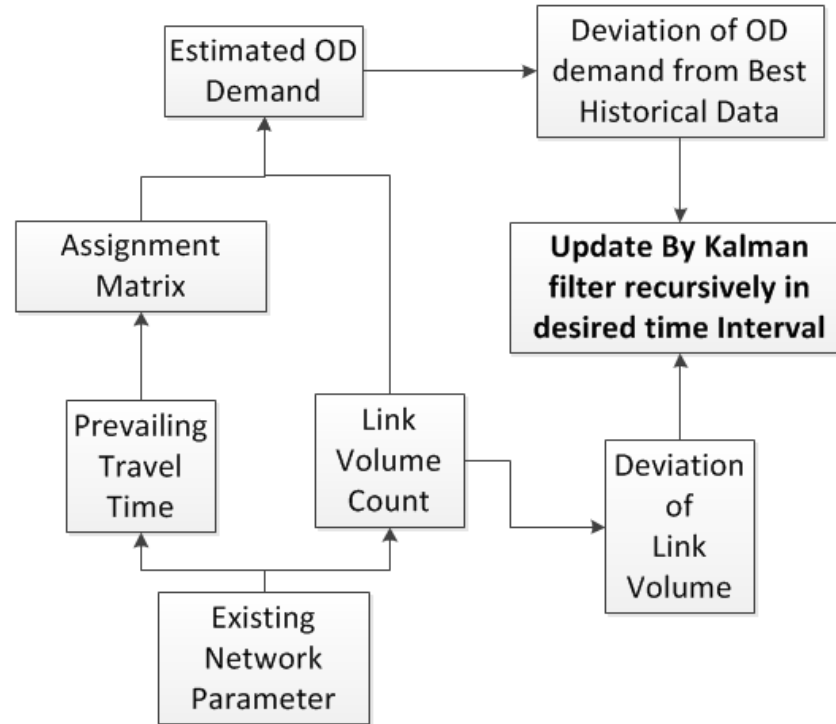
- Road user plan their route largely based on travel time.
- The route volume is the result of route choice
- The route volume affect the prevailing travel time
- The recursive updating nature of Kalman Filter is suitable for this framework

# Proposed Analytical Framework

Typical Traffic Assignment Steps



Proposed OD Estimation Framework



- Bluetooth readers provide travel time information
- Route choice is derived from travel time information
- RTMS's provide volume counts

# Recursive Kalman Filter

Prediction Step: 
$$x_{ij}(t+1) - x_{ij}^H(t+1) = B_t [x_{ij}(t) - x_{ij}^H(t)] + w(t) \quad (1)$$

Updating Step: 
$$y_l(t) - y_l^H(t) = A_t [x_{ij}(t) - x_{ij}^H(t)] + v(t) \quad (2)$$

$x_{ij}(t)$ -demand in t time interval from origin i to destination j

$x_{ij}^H(t)$ -historical or outdated demand in t time interval from origin i to destination j

$y_l(t)$ -real-time link volume counts vector

$y_l^H(t)$ -historical link volume counts vector

$B_t$  -state transition matrix between two sequential time intervals t and t+1

$A_t$  -assignment matrix at time interval t

$w(t)$ -random error of prediction

$v(t)$ - random error of field measurement



# Advantages of the Proposed Framework

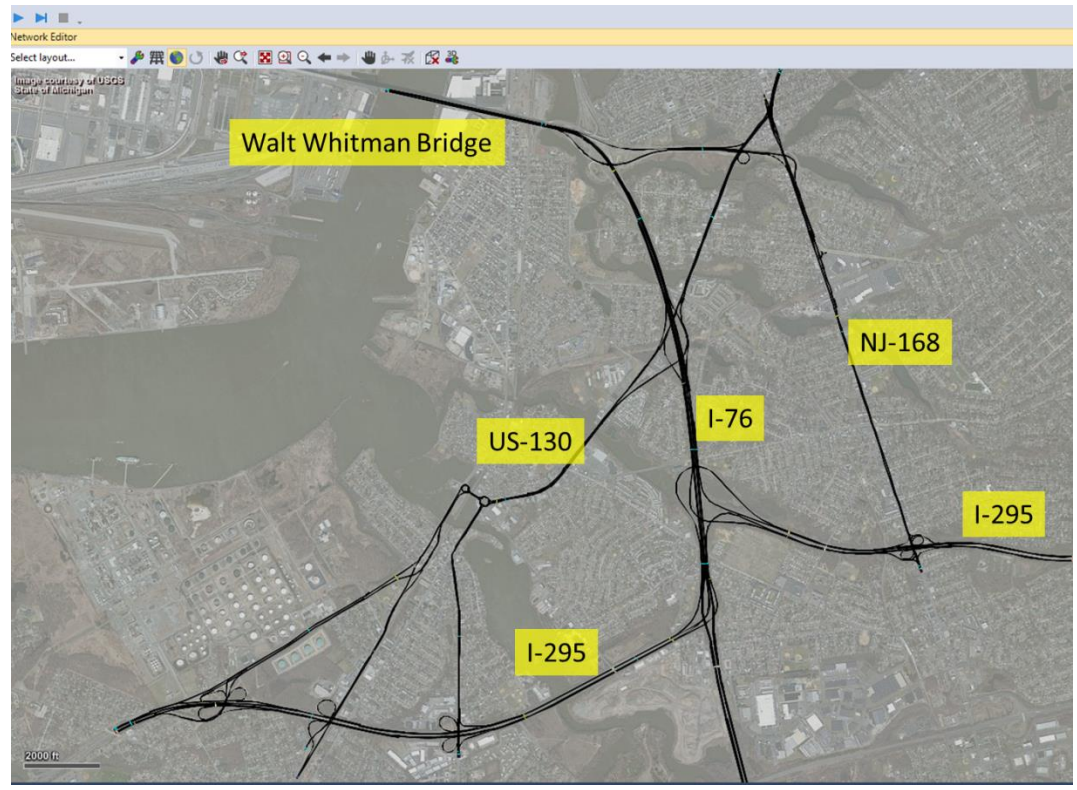
- Different sources of real-time traffic flow information are incorporated and utilized.
- Only the most-travelled routes in the network are considered in order to reduce the computational expenses.
- The estimation result will be evaluated and compare to historical results to ensure the consistency and accuracy of the estimation.
- The three modules are relatively independent, therefore each can be substituted with other assignment modules or data collection modules.

## Disadvantage of the Proposed Framework

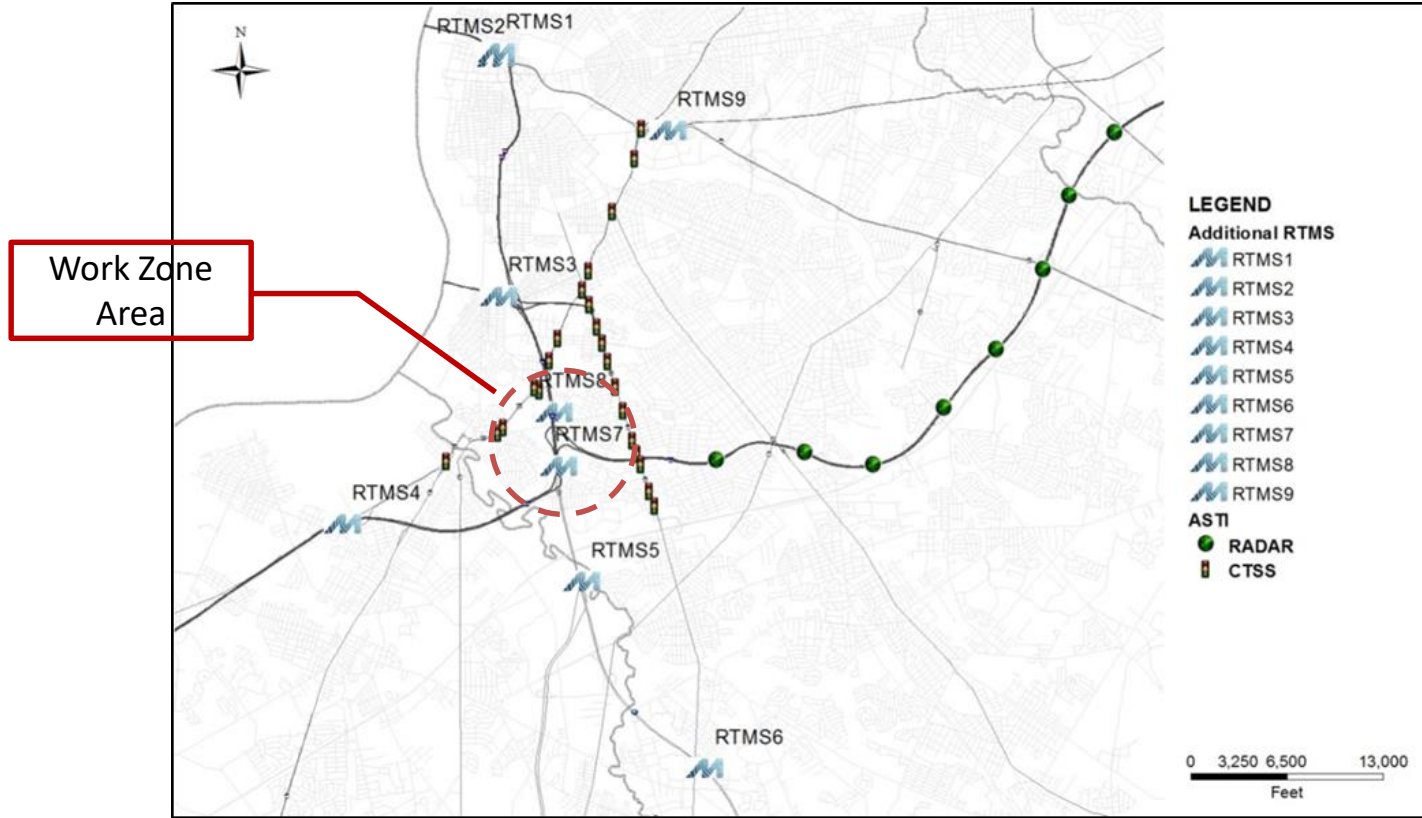
- Errors may occur due to the approximation applied under low market penetrations of Bluetooth devices.
- Need more time and efforts for model calibration due to a case-by-case basis when it comes to implementation.
- Engineering judgment of network travel pattern can affect the accuracy of the model.

# Proof-of-Concept Test for I-295 Work Zone Monitoring

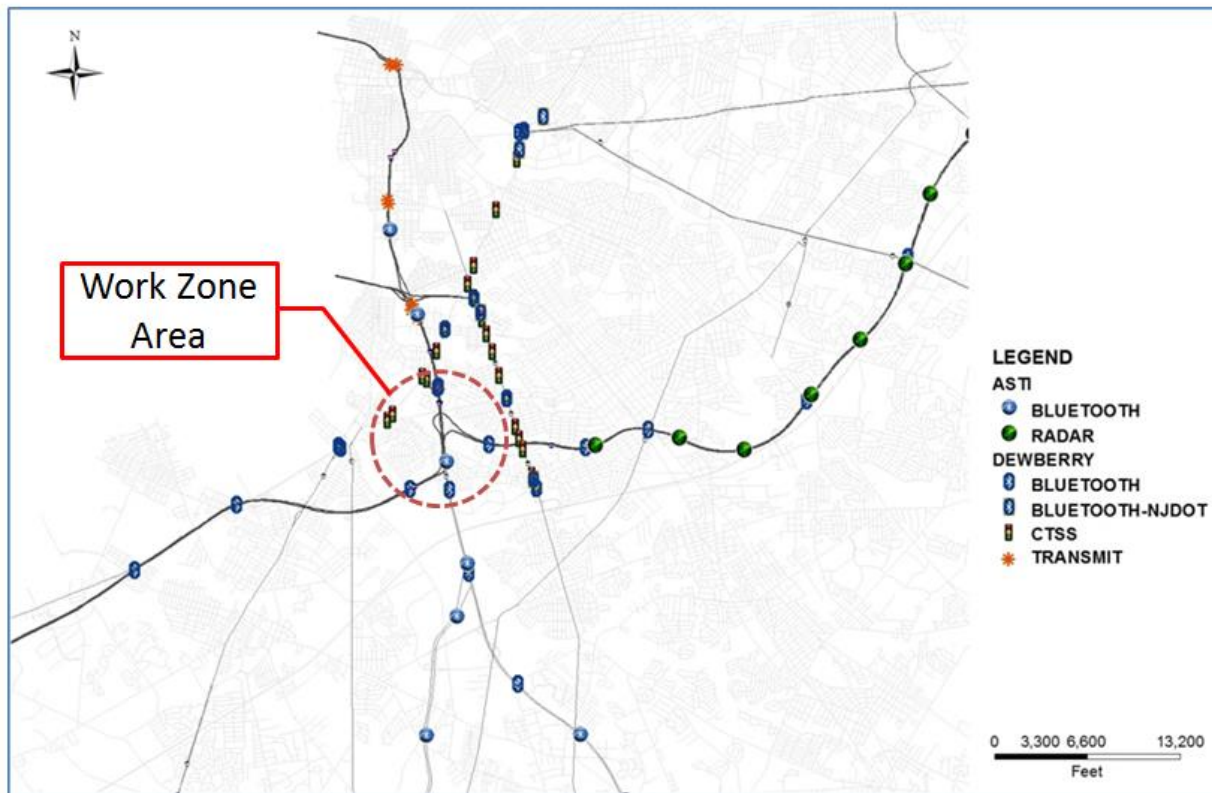
- The proposed framework will be tested for I-295 Direct Connect roadway reconfiguration work zone.
- ITS device installation is currently in progress, while experiencing delays.



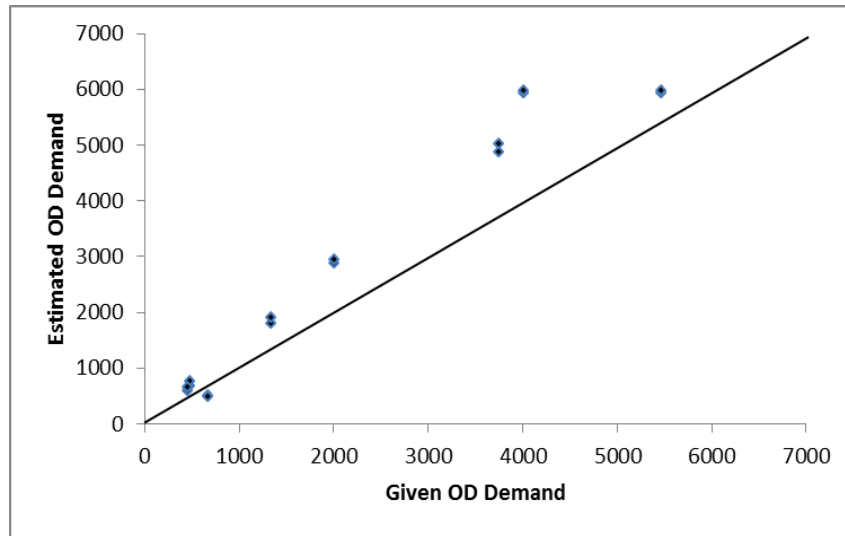
# Deployment Plan of RTMS's



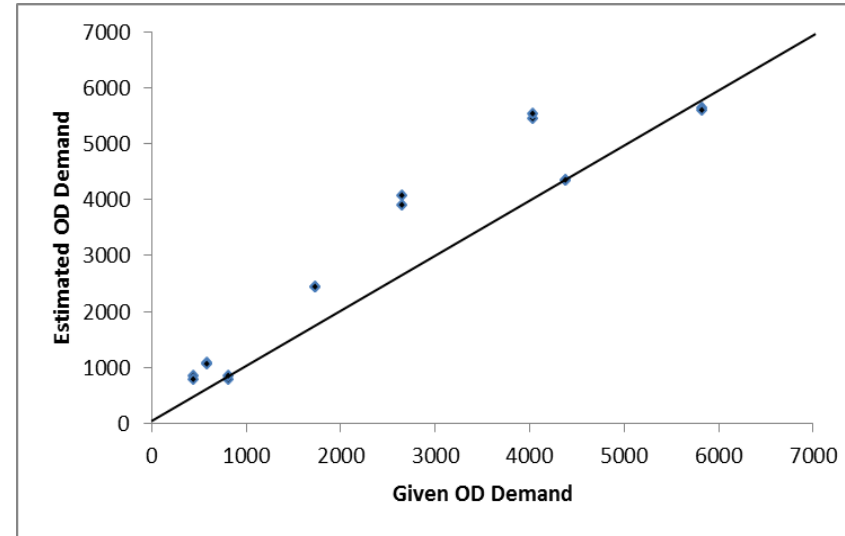
# Deployment Plan of Bluetooth Readers



# Preliminary Results from Simulation Test Bed



O-D demand estimated  
for 3:00 to 4:00pm



O-D demand estimated  
for 4:00 to 5:00pm

- Each point represents one pair of O-D demand
- Kalman Filter was not yet implemented in the test

# Future Study

- Modular enhancement (e.g. route travel time estimation based on partly knowledge of the route travel time)
- Application upon receipt of the field data.
- Comprehensive evaluation of the estimation results.
- Investigation its application under congested network.

**THANK YOU FOR YOUR ATTENTION  
QUESTIONS?**